

# Man-Machine Integration Design and Analysis System: MIDAS

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www-midas.arc.nasa.gov





# **MIDAS Applications**

### NASA:

**Advanced Air Traffic Technologies High Speed Research Program** 

## **Army:**

**AirWarrior** 

**CH-47** 

### Other:

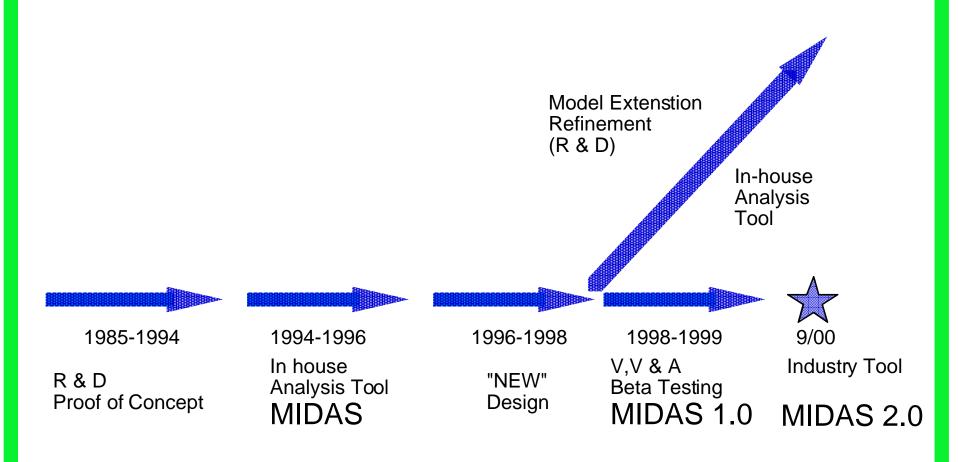
**Nuclear Power Plant** 

911





# **MIDAS Development Schedule**







# Why Redesign?

## Implementation:

3 languages (C, C++, LISP)

500k lines of code

250k MIDAS

250k Jack® (U of Penn, Transom)

**Legacy Code** 

**User Interface** 





# Why Redesign?

## **Functionality:**

Difficult to use

**Multiple Operators** 

Long Term Memory (LTM), working memory distinction

Reactive Action Packages (RAPs)

**Multiple Resource Attention Model** 

**Internal and External Vision** 

**Audition** 





## **MIDAS Models**

**Perception:** 

**Vision** 

**Audition** 

**Central Processing and Memory:** 

**Attention** 

**Working Memory** 

**Long Term Memory** 

(Reactive Action Packages)

**Process Models:** 

Workload

**Situational Awareness** 





# **Perception: Vision**

### **External**

Peripheral = 160 degrees

Foveal = 2.5 degrees

Perception level f(dwell time, perceivability)

Perceivability f(visibility, size, distance, local contrast ratio)

Levels of Perception = detection, recognition, identification

### Internal

Symbolic (check read)

Digital (exact value)

Text (character string)





# **Perception: Audition**

## **Two Stages of Processing:**

- 1) Detection
- 2) Comprehension

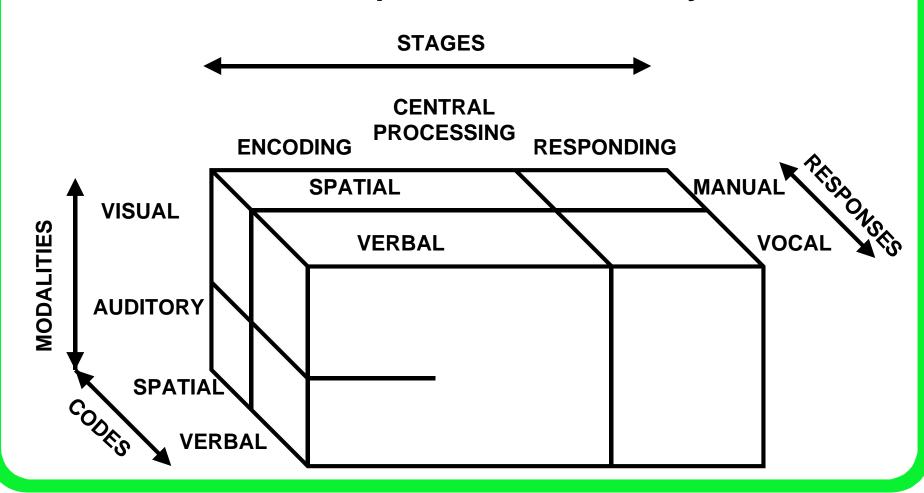
Content: verbal strings or signals
All or none processing -- partial processing
planned (semantic parsing)
Interrupts currently disrupts entire message

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# Central Processing and Memory: Attention

**RDEC** 

## Wickens, 1980 Multiple Resource Theory



**RDEC** 



### **Contains:**

- a) Current Context --Instantiated by sensory inputUsed to select RAPs from LTM
- b) Task Agenda --Contains currently active goals

## Manages:

- a) New Events
- b) Goal Priorities
- c) Plan Execution

**RDEC** 



# Declarative Knowledge: Expertise, Facts

Procedural Knowledge:

Reactive Action Packages (Firby, 1989)

RAP Library



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# Reactive Action Packages: RAPs

RAPs are based on "sketchy" planning.

**Current Context (working memory) --> LTM** 

**Current Context (n) = RAP Context(n)** 

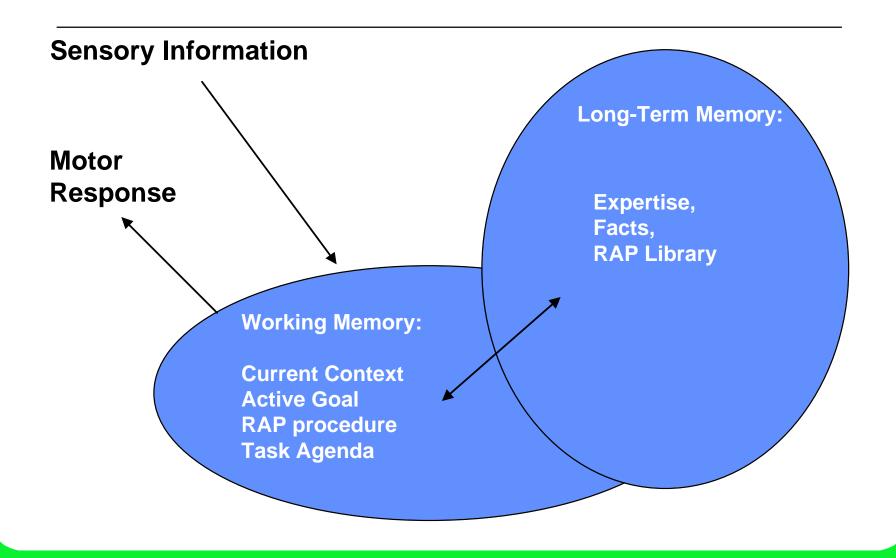
RAP Context(n) contains:

procedures for task execution
success criteria for completion





# **RAP Example**







# **Key Difference Functionality**

### **Old MIDAS:**

Behavior is controlled by top-down goal decomposition. Specify conditionals in detail.

## **New Design:**

Behavior is controlled by an interaction of topdown goals and environmentally driven contexts. Conditionals don't need to be specified, but emerge as behaviors.





## **Process Models**

Workload (McCracken and Aldrich, 1988)

Visual, Auditory, Cognitive, Psychomotor 1-7 Scale based on Task Primitives

Situational Awareness (Shively, Brickner & Silbiger, 1997)

Situational Elements
Context-Sensitive Higher Order Nodes



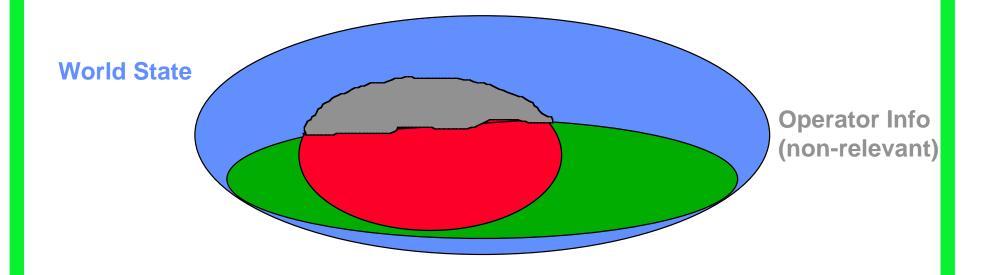
# Situational Awareness (Shively, Brickner & Silbiger)

RDEC

Ratio of *relevant* knowledge that the user has to the *relevant* information needed

operator know (context)

info needed (context)







### **Plans**

Alpha Release - Sept 30, 1998

Beta Release - Dec 31, 1998

**Boeing - Philadelphia** 

**Israel Air Force** 

Validation - thru Dec 31, 1999

**Blue Ribbon Panel - Spring, 1999** 

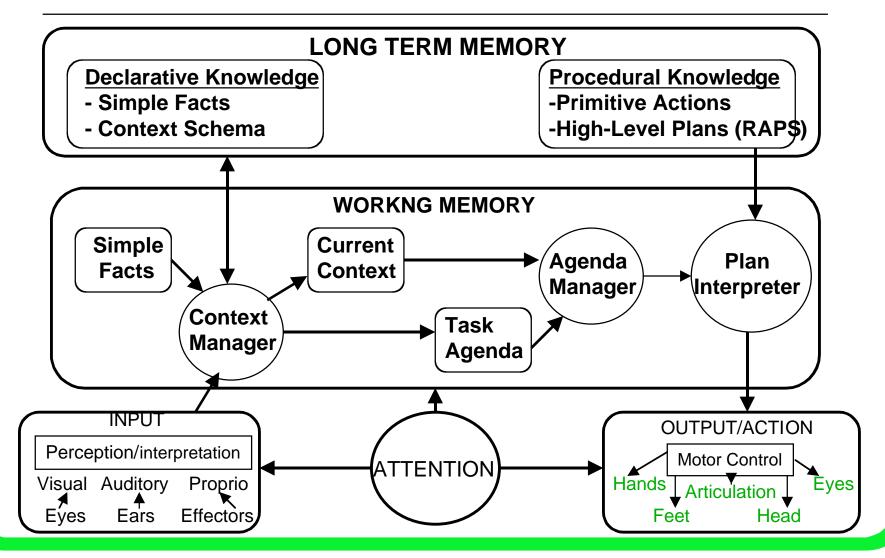
**Empirical Validation -**

**Usability Testing -**

**Industry Release - Sept 30, 2000** 

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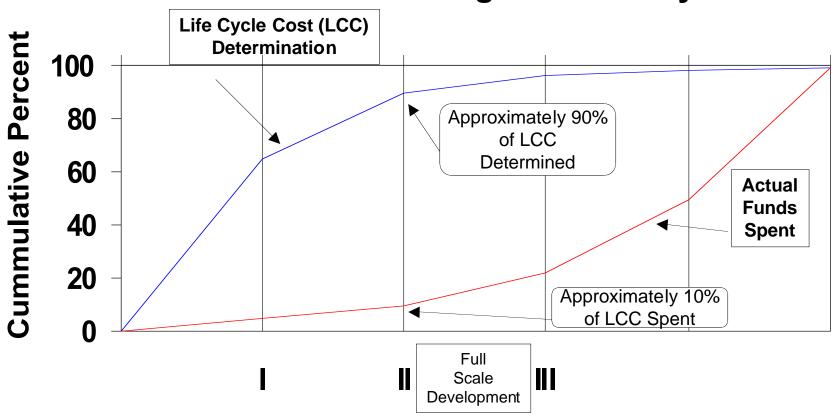






# Life Cycle Cost Leverage Defense Systems

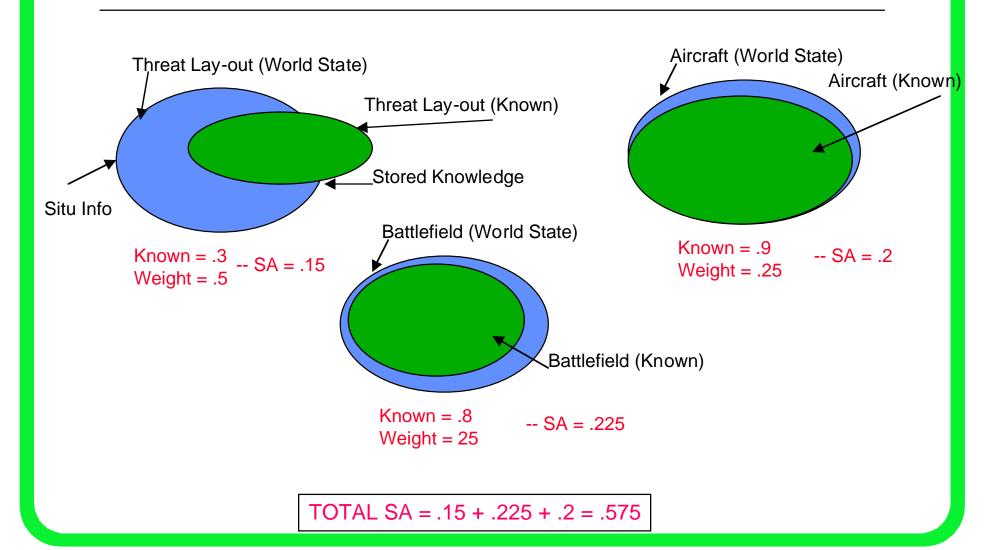
# Acquisition Community is Focused on Cost Reduction Throughout Life Cycle







# **SA Example**







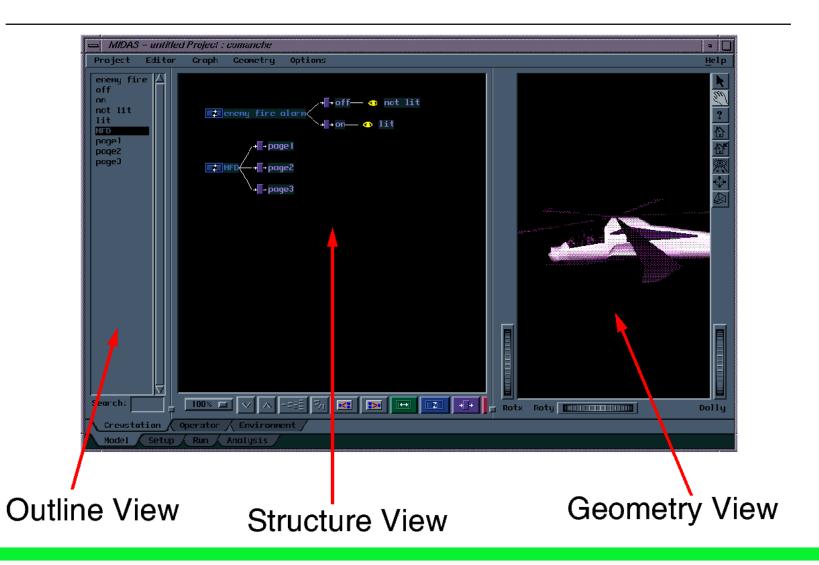
# **Run-time Display - GUI**







## **Crewstation Editor - GUI**

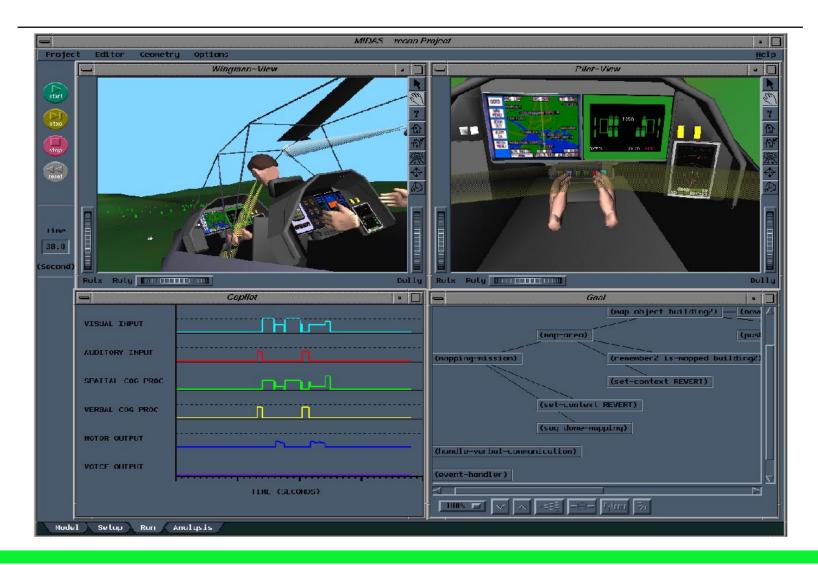






# Run-time Display - Co-pilot - GUI

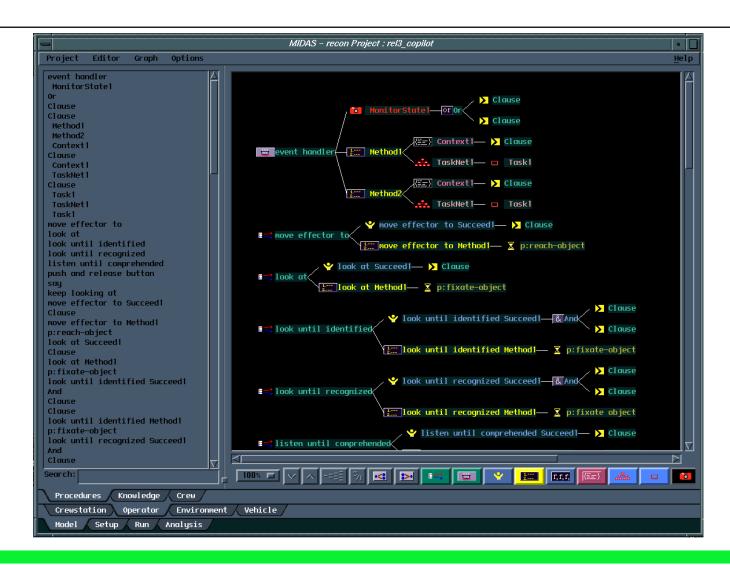
**RDEC** 







## **Procedure Editor - GUI**







## **Tab Format for GUI Editors**

